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application version: 00.270911

PROGRAMMING MANUAL
ZeelProg PDCI-11V(T)

Supported control units: **PDCI-11V, PDCI-11VT**

ZeelProg is PC application for programming ZEELTRONIC engine *control units*.
For programming special PC-USB programmer is needed.

➲ ***ZeelProg*** automatically detects PC-USB programmer connection and enables all functions (without PC-USB programmer, ***ZeelProg*** application is locked).
➲ ***ZeelProg*** automatically detects type of engine *control unit* connected to PC-USB programmer.

CONTENT

ZeelProg SOFTWARE INSTALLATION GUIDE

CD content:
- driver (USB programmer driver)
- NET Framevork
- ZeelProg

Software can be also downloaded from web site:
http://www.zeeltronic.com/page/zeelprog.php

ZeelProg application can be installed on Windows XP/Vista.
"NET Framework 3.5" needs to be installed.

Installation:
① Insert CD-ROM and browse content.
② Install USB programmer driver with running "CDM20600.exe" from CD-ROM "driver" directory.
③ Install *ZeelProg* with running "setup ZeelProg.exe" from CD-ROM "ZeelProg" directory.

If *ZeelProg* does not start, install "NET Framework" from CD-ROM "NET Framework" directory.

ZeelProg USER INTERFACE

Auto detection

*Zeelprog* automatically detects USB-Programmer and type of *control unit*.

⇨ Programmer connected, product (*control unit*) connected:

Programmer	Product Connected	Product Software ver.
connected	PDCI-11VT	25.120326

⇨ Programmer connected, product (*control unit*) not connected:
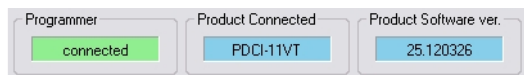
Programmer	Product Connected	Product Software ver.
connected	not connected	
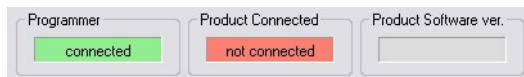
⇨ Programmer connected, product (*control unit*) not supported:

Programmer	Product Connected	Product Software ver.
connected	not supported	20.290110
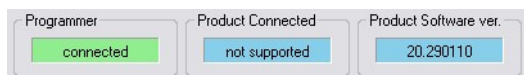
⇨ Programmer not connected, product (*control unit*) not connected:

Programmer	Product Connected	Product Software ver.
not connected	not connected	
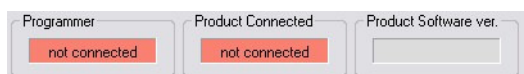
Menu structure

File   Monitor   About

⇨ **File menu** is active when PC-USB programmer is connected
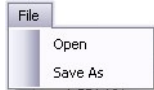
File
  Open
  Save As

Open   → Open an existing *.zee file
Save As   → Save all parameters to *.zee file

⇨ **Monitor** is active when *control unit* is connected to PC-USB programmer.
   Clicking on the **Monitor** opens Monitor window.

Monitor - ZEELTRONIC Performance Ignition Systems

RPM: 0
IGNITION: 0,0   [deg]
PV: 0   [%]

TPS: 0%
Power Jet 1:   ON
Duty Solenoid: 0%
Shift light: OFF
Ign. map: #1
PV map: #1

Exit

⇨ Clicking on **About** opens About window and show some basic information about
   ZeelProg application.

About ZeelProg PDCI-11V(T)

zeeltronic
PERFORMANCE IGNITION SYSTEMS

Supported products: PDCI-11V, PDCI-11VT

Version: 00.270911
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Ignition Parameters

Ignition Parameters

Ignition Map #1

| 12 | Nr. of Points |

TPS 100%

Point 1	Point 2	Point 3	Point 4	Point 5	Point 6	Point 7	Point 8	Point 9	Point 10	Point 11	Point 12	
1500	3000	4000	5000	6000	7000	8000	9000	10000	11000	12000	13000	RPM
15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	deg

TPS 66%

Point 1	Point 2	Point 3	Point 4	Point 5	Point 6	Point 7	Point 8	Point 9	Point 10	Point 11	Point 12	
1500	3000	4000	5000	6000	7000	8000	9000	10000	11000	12000	13000	RPM
15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	deg

TPS 0-33%

Point 1	Point 2	Point 3	Point 4	Point 5	Point 6	Point 7	Point 8	Point 9	Point 10	Point 11	Point 12	
1500	3000	4000	5000	6000	7000	8000	9000	10000	11000	12000	13000	RPM
15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	deg

Ignition Map #2

| 12 | Nr. of Points |

TPS 100%

Point 1	Point 2	Point 3	Point 4	Point 5	Point 6	Point 7	Point 8	Point 9	Point 10	Point 11	Point 12	
1500	3000	4000	5000	6000	7000	8000	9000	10000	11000	12000	13000	RPM
15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	deg

TPS 66%

Point 1	Point 2	Point 3	Point 4	Point 5	Point 6	Point 7	Point 8	Point 9	Point 10	Point 11	Point 12	
1500	3000	4000	5000	6000	7000	8000	9000	10000	11000	12000	13000	RPM
15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	deg

TPS 0-33%

Point 1	Point 2	Point 3	Point 4	Point 5	Point 6	Point 7	Point 8	Point 9	Point 10	Point 11	Point 12	
1500	3000	4000	5000	6000	7000	8000	9000	10000	11000	12000	13000	RPM
15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	15,0	deg

☐ Ign. Map Switch

| 1 | Select Ignition Map |

34,0	Static Angle [°]
0,0	Advance [°]
30	Delay Compensation [us]

⇨ **Nr. of Points** for each ignition map can be set from 4 to 12.

⇨ **RPM** of each ignition point can be set from 100rpm to 20000rpm in 100rpm steps.

⇨ **deg**...advance of each ignition point can be set from 0deg to 85deg in 0,1deg steps

⇨ **Static Angle** is pickup advance position from TDC (Top Dead Centre)

⇨ **Advance**...advances, or retards whole ignition map from -10deg to 10deg in 0,1deg steps. Positive value advances and negative value retards.

⇨ **Delay Compensation**...ensure correct ignition angle through whole revs. Default value is 30us.

⇨ **Ignition Map Switch**...enables, or disables ignition map switch. Ignition map can be selected with switch, when function is enabled.

⇨ **Select Ignition Map**...selection is active only when **Ignition Map Switch** is not enabled.

Misc Parameters

⇨ **Pulses per Rev**...set to 1 for single cylinder and set to 2 for wasted spark twin cylinder.

⇨ **Rev limit**...limits maximum revolutions. Set to maximum 20000rpm in 100rpm steps.

⇨ **Shift light**...activate shift light output above programmed revs. Set to maximum 20000rpm in 100rpm steps.

⇨ **TCT mode**... Throttle Close spark Termination mode, reduces number of sparks above 8000rpm (spark is active every third revolution), when throttle is closed. TCT mode ensure better engine cooling.

⇨ **TPS Enable**... enable, or disable TPS (Throttle Position Sensor).

⇨ **TPS closed [0%]**... for correct TPS operation, TPS close position must be calibrated!

⇨ **TPS opened [100%]**... for correct TPS operation, TPS open position must be calibrated!

⇨ **Smart Shift**... enable, or disable Smart Shift. Smart shift function automatically adjusts kill time for different revs. Shift kill time must be always set, as basic kill time.

⇨ **Kill Time**... for shifting without using clutch - shift sensor is required. Function is disabled with setting to 0ms.

⇨ **Stop Switch Mode: Low Level Stop**... engine stops with low level signal (stop switch connected to the ground)

⇨ **Stop Switch Mode: High Level Stop**... engine stops with high level signal (stop switch is opened)

Solenoid parameters

⇨ **Solenoid Output Type**... Solenoid output function can be configured as Power Jet 2, or Duty Solenoid. Duty solenoid is used for adjusting A/F ratio on some carburettors.
① **Power Jet 2 'ON' rpm**... revs for activating Power Jet 2
② **Power Jet 2 'OFF' rpm**... revs for deactivating Power Jet 2
③ **Power Jet 2 'ON' TPS**... throttle position for activating Power Jet 2
④ **Power Jet 2 'OFF' TPS**... throttle position for deactivating Power Jet 2
⇨ **RPM** of each Duty Solenoid point can be set from 100rpm to 20000rpm in 100rpm steps.
⇨ **%** of each Duty Solenoid point can be set from 0% to 100%.

Power Jet 2 example:
Power jet 2 ON (RPM) = 5000rpm
Power jet 2 OFF (RPM) = 8000rpm
Power jet 2 ON (TPS) = 0%TPS
power jet 2 OFF (TPS) = 100%TPS

Power jet is switched on when revs are between 5000-8000rpm and throttle position is between 0-100%, otherwise power jet is switched off.

PV PARAMETERS

⇨ **Nr. of Points** for each PV map can be set from 2 to 8.
⇨ **RPM** of each PV point can be set from 100rpm to 20000rpm in 100rpm steps.
⇨ **%**...PV position of each PV point can be set from 0% to 100% in 1% steps.
⇨ **Power-up Test**...enables, or disables PV test at switching on power supply.
⇨ **Select PV Map**...selecting active PV map.
⇨ **Deviation**...prevents 'hunting' of PV servo.
⇨ **Close Position** of PV servo. Close position is 0% on PV map.
⇨ **Open Position** of PV servo. Open position is 100% on PV map.
⇨ **Test Close**...clicking on **Test Close** button, opens Test Close window. Function is
   active when PC-USB programmer and *control unit* are connected.
⇨ **Test Open**...clicking on **Test Open** button, opens Test Open window. Function is
   active when PC-USB programmer and *control unit* are connected.
⇨ **PV Map Switch**...enables, or disables PV map switch. PV map can be selected with
switch, when function is enabled.

POWER JET 1 PARAMETERS
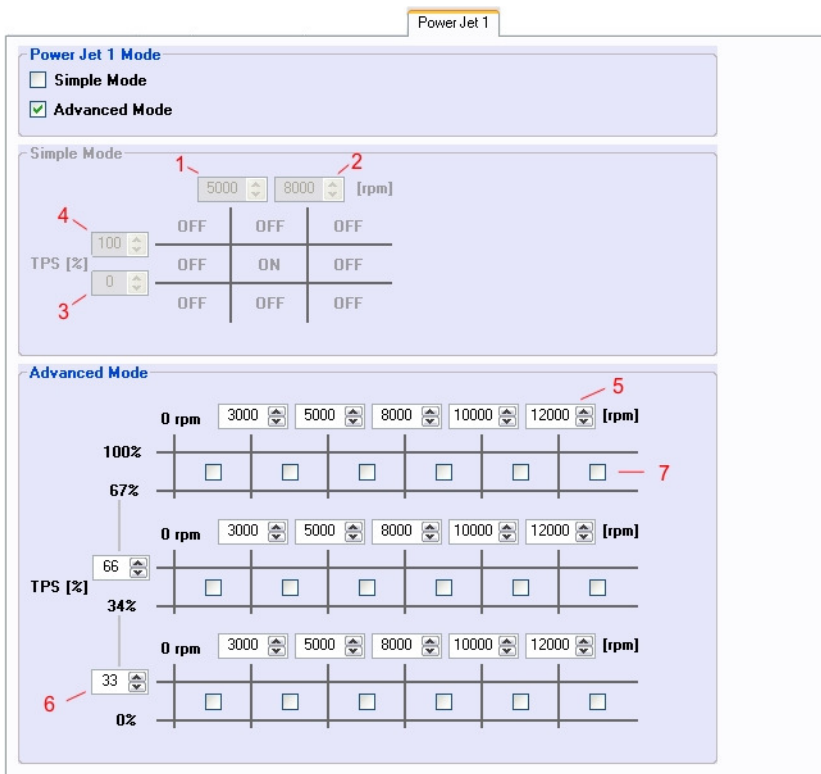
⇨ **Power Jet 1 mode** ... select simple, or advanced power jet mode

Power Jet 1 Simple Mode:

① ... revs for activating Power Jet 1

② ... revs for deactivating Power Jet 1

③ ... throttle position for activating Power Jet 1

④ ... throttle position for deactivating Power Jet 1

Power Jet 1 Advanced Mode:

⑤ ... rev points

⑥ ... upper TPS range

⑦ ... check for switching 'on' and uncheck for switching 'off' power jet 1

PROGRAMMING AND SETTING NEW PARAMETERS

➲ While programming or reading, *control unit* does not need to be connected to power supply, because it is supplied through PC-USB programmer.

Changing control unit parameters

① Read parameters from connected *control unit*, by pressing **Read** button.

| Read | ... |

Progress bar indicate read and verify process.

Successful reading is indicated as: | Read | ok |
Error while reading is indicated as: | Read | error |
If error occurs, then repeat reading.

② Change parameters
③ Program parameters to connected *control unit*, by pressing **Program** button.

| Program | ... |

Progress bar indicate program and verify process.

Successful programming is indicated as: | Program | ok |
Error while programming is indicated as: | Program | error |
If error occurs, then repeat programming.

Make new *.zee file without connecting control unit

① Connect PC-USB programmer to PC.
② Set parameters
③ Save parameters by clicking **Save As** from **File menu**.

| File |
| Open |
| Save As |
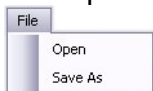
TPS Close Position [0%]

For correct operation of TPS function, TPS close position must be calibrated!

| Calibrate | 230 ⬍ | **TPS closed (0%)** |

TPS close position can be set manually by entering number, or calibrated by clicking on **Calibrate** button.
Using **Calibrate** function is more recommended.

Clicking on **Calibrate** button opens **Calibrate TPS Close Position** window.

Calibrate TPS Close Position ✖
| Hold throttle at full close position ! |
| 62 | TPS position | OK |
| | | Cancel |

⇨ to finish calibration: hold throttle at full close position and press **OK** button
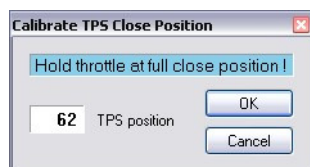⇨ to cancel calibration: press **Cancel** button
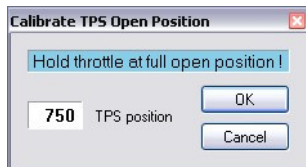
TPS Open Position [100%]

For correct operation of TPS function, TPS open position must be calibrated!

TPS open position can be set manually by entering number, or calibrated by clicking on **Calibrate** button.
Using **Calibrate** function is more recommended.

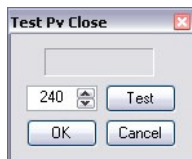Clicking on **Calibrate** button opens **Calibrate TPS Open Position** window.

⇨ to finish calibration: hold throttle at full open position and press **OK** button
⇨ to cancel calibration: press **Cancel** button

Set PV close position

⇨ Clicking on **Test Close** button opens Test Close window.
Function is active when PC-USB programmer and *control unit* are connected.
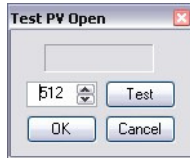

⇨ PV servo close position can be tested before confirming... PV servo moves to close position, after clicking on **Test** button.
⇨ If PV servo can't move to close position then **error 1** will occur. To clear **error 1** change close position and click on **Test** button.
⇨ Click on **OK** button to confirm close position, or **Cancel** to keep old close position.

Set PV open position

`512 ⬍` **Open Position** `Test Open`

⇨ Clicking on **Test Open** button opens Test Open window.
  Function is active when PC-USB programmer and *control unit* are connected.

Test PV Open ✕

`512 ⬍` `Test`
`OK` `Cancel`

⇨ PV servo open position can be tested before confirming... PV servo moves to open position, after clicking on **Test** button.
⇨ If PV servo can't move to open position then **error 1** will occur. To clear **error 1** change open position and click on **Test** button.
⇨ Click on **OK** button to confirm open position, or **Cancel** button to keep old open position.

MONITOR FUNCTION

⇨ **Monitor** function is active when *control unit* is connected to PC-USB programmer.

`File   Monitor   About`

Clicking on **Monitor** opens Monitor window.

Monitor - ZEELTRONIC Performance Ignition Systems

RPM:	**0**
IGNITION:	**0,0** [deg]
PV:	**0** [%]
TPS:	0%
Power Jet 1:	ON
Duty Solenoid:	0%
Shift light:	OFF
Ign. map:	#1
PV map:	#1

`Exit`

⇨ Monitor show engine revolution, ignition advance angle, PV position, TPS position, selected ignition map, selected PV map, shift light operation, rev limit operation, power jet 1 operation, duty solenoid operation.

NOTES